

# Dynamical Systems Generated by Mappings with Delay

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Automaton transformation of the space of all one-side infinite words over the alphabet  $\{0, 1, \dots, p - 1\}$ , where  $p$  is a prime number, is continuous transformation (w.r.t. the  $p$ -adic metric) of the ring of  $p$ -adic integers  $\mathbb{Z}_p$ .

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Moreover, a mappings that are realized by (synchronous) automata satisfy the  $p$ -adic Lipschitz condition with constant equal 1.

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Moreover, a mappings that are realized by (synchronous) automata satisfy the  $p$ -adic Lipschitz condition with constant equal 1.

In the  $p$ -adic ergodic theory automata are  $p$ -adic dynamical systems and automata mappings, in their turn, are a continuous (in particular, 1-Lipschitz) transformations of the space  $\mathbb{Z}_p$ .

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The objects of the study are mappings with delay realized by asynchronous automata in the context of the  $p$ -adic dynamics. The ergodic and more generally measure-preserving  $p$ -adic dynamical systems are explored.

# Outline

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An (synchronous) **automaton (or, letter-to-letter transducer)** is a 6-tuple  $\mathcal{A} = (\mathcal{I}, \mathcal{S}, \mathcal{O}, h, g, s_0)$ , where

- $\mathcal{I}$  is a non-empty finite set, the input alphabet,
- $\mathcal{O}$  is a non-empty finite set, the output alphabet,
- $\mathcal{S}$  is a non-empty (possibly, infinite) set of states,
- $h: \mathcal{I} \times \mathcal{S} \rightarrow \mathcal{S}$  is a state update function,
- $g: \mathcal{I} \times \mathcal{S} \rightarrow \mathcal{O}$  is an output function, and
- $s_0 \in \mathcal{S}$  is fixed;  $s_0$  is called the initial state.

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Asynchronous automaton is defined in a similar way, except for output function. Denote the set of finite output words via  $\mathcal{O}^*$ .

An **asynchronous automaton** is a 6-tuple  $\mathcal{B} = (\mathcal{I}, \mathcal{S}, \mathcal{O}, h, g, s_0)$ , where

- $\mathcal{I}, \mathcal{O}$  are finite alphabets,  $\mathcal{S}$  is a set of states,
- $h: \mathcal{I} \times \mathcal{S} \rightarrow \mathcal{S}$  is a state update function,
- $g: \mathcal{I} \times \mathcal{S} \rightarrow \mathcal{O}^*$  is an output function, and
- $s_0$  is an initial state.

Note that set of states  $\mathcal{S}$  **could be an infinite**, and in this case an automaton is called infinite.



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Roughly speaking, **asynchronous automaton** is an **letter-to-word transducer** that converts an input string of arbitrary length to an output string. The transducer reads one symbol at a time, changing its internal state and outputting a finite sequence of symbols at each step.

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Roughly speaking, **asynchronous automaton** is an **letter-to-word transducer** that converts an input string of arbitrary length to an output string. The transducer reads one symbol at a time, changing its internal state and outputting a finite sequence of symbols at each step. **Asynchronous transducers are a natural generalization of synchronous transducers, which are required to output exactly one symbol for every symbol read.**

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For example, the asynchronous automaton represented by  
Moore diagram: Starting in initial state, automaton converts  
any first input symbol to empty word.

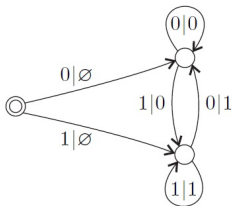


Figure : Example of an asynchronous automaton

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We consider only **accessible** automata: where any state  $s \in \mathcal{S}$  is reachable from initial state  $s_0$ ; that is, given state  $s \in \mathcal{S}$ , there exist a finite input word  $u$  such that after the word  $u$  has been fed to the automaton, the automaton reaches the state  $s \in \mathcal{S}$ .

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We assume further that both alphabets  $\mathcal{I}$  and  $\mathcal{O}$  are  $p$ -elements:  $\mathcal{I} = \mathcal{O} = \mathbb{F}_p = \{0, 1, \dots, p-1\}$ .

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We assume further that both alphabets  $\mathcal{I}$  and  $\mathcal{O}$  are  $p$ -elements:  $\mathcal{I} = \mathcal{O} = \mathbb{F}_p = \{0, 1, \dots, p-1\}$ . A simple example of an automaton is the **2-adic adding machine**:  $x \mapsto x+1$ ,  $\mathcal{A} = (\mathcal{I} = \mathbb{F}_2, \mathcal{S} = \{s_0, s_1\}, \mathcal{O} = \mathbb{F}_2, h, g, s_0)$ , where

$$h(0, s_0) = s_1; h(1, s_0) = s_0,$$

$$g(0, s_0) = 1; g(1, s_0) = 0,$$

$$h(i, s_1) = s_1; g(i, s_1) = i,$$

for  $i \in \mathcal{I} = \mathbb{F}_2$ .

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An automaton  $\mathcal{A} = (\mathcal{I}, \mathcal{S}, \mathcal{O}, h, g, s_0)$  transforms input words (w.r.t the alphabet  $\mathbb{F}_p$ ) of length  $n$  into output words of length  $n$ , that is, an automaton  $\mathcal{A}$  maps the set  $W_n$  of all words of length  $n$  into  $W_n$ .

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$$x = x_0 + x_1 \cdot p + \dots + x_{n-1} \cdot p^{n-1} = \sum_{i=0}^{n-1} x_i \cdot p^i.$$



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$$x = x_0 + x_1 \cdot p + \dots + x_{n-1} \cdot p^{n-1} = \sum_{i=0}^{n-1} x_i \cdot p^i.$$

This number  $x$  can be considered as an element of the residue ring  $\mathbb{Z}/p^n\mathbb{Z}$  modulo  $p^n$ . Thus, every automaton  $\mathcal{A}$  corresponds a map  $f_n$  from  $\mathbb{Z}/p^n\mathbb{Z}$  to  $\mathbb{Z}/p^n\mathbb{Z}$ , for every  $n = 1, 2, 3, \dots$

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The function  $f_n: \mathbb{Z}/p^n\mathbb{Z} \rightarrow \mathbb{Z}/p^n\mathbb{Z}$  can be considering as the mapping in the space of infinite words over the alphabet  $\mathbb{F}_p$ . The latter can be identified with the ring of  $p$ -adic integers  $\mathbb{Z}_p$ .

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Every automaton  $\mathcal{A}$  *defines a map  $f_{\mathcal{A}}$  from ring of  $p$ -adic integers  $\mathbb{Z}_p$  to itself*: Given an infinite string

$x = \dots x_{n-1} \dots x_1 x_0$  over  $\mathbb{F}_p$  we consider a  $p$ -adic integer  $x = x_0 + x_1 \cdot p + \dots + x_{n-1} \cdot p^{n-1} + \dots = \sum_{i=0}^{\infty} \delta_i(x) \cdot p^i$ ,

where  $\delta_i$  are coordinate functions valued in  $\mathbb{F}_p$ . Here  $\delta_i$  depends only on the coordinates  $x_0, x_1, \dots, x_i$  of the variable  $x$ :  $\delta_i = \delta_i(x_0, x_1, \dots, x_i)$ .

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where  $\delta_i$  are coordinate functions valued in  $\mathbb{F}_p$ . Here  $\delta_i$  depends only on the coordinates  $x_0, x_1, \dots, x_i$  of the variable  $x$ :  $\delta_i = \delta_i(x_0, x_1, \dots, x_i)$ .

For every  $x \in \mathbb{Z}_p$ , we put  $\delta_i(f_{\mathcal{A}}(x)) = g(\delta_i(x), s_i)$ ,  $i = 0, 1, 2, \dots$  where  $s_i = h(\delta_{i-1}(x), s_{i-1})$ ,  $i = 1, 2, \dots$

So, we say, that map  $f_{\mathcal{A}}$  is *automaton function* (or, automaton map) of the automaton  $\mathcal{A}$ .

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Similar way, we can consider **asynchronous automata**: An asynchronous automaton  $\mathcal{B} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, h, g, s_0)$  performs a **transformation**  $f_{\mathcal{B}}: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$ .

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Synchronous automaton function  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  satisfies  
1-Lipschitz condition:

$\|f(x) - f(y)\|_p \leq \|x - y\|_p$  for any  $x, y \in \mathbb{Z}_p$ , where  $\|\cdot\|_p$  is  
the  $p$ -adic norm.

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For 1-Lipschitz functions the following natural question  
arises: **Can any 1-Lipschitz mapping be generated by some  
(synchronous) automaton?**

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The answer is “yes”: The class of all (synchronous) automata functions coincides with the class of all 1-Lipschitz mappings from  $\mathbb{Z}_p$  to  $\mathbb{Z}_p$ .

## Theorem (V.S. Anashin)

The automaton function  $f_{\mathcal{A}}: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  of the synchronous automaton  $\mathcal{A} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, S, O, s_0)$  is 1-Lipschitz.

Conversely, for every 1-Lipschitz function  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  there exists an synchronous automaton  $\mathcal{A} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, S, O, s_0)$  such that  $f = f_{\mathcal{A}}$ .



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We note, that in general case 1-Lipschitz function generated by some infinite automaton, i.e. the space of states  $\mathcal{S}$  of automaton is infinite.

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The description of finite automata functions was given by Vuillemin, although only for  $p = 2$ . V.S. Anashin and T.Smyshlyaeva solved this problem for arbitrary  $p$ , using a coordinate functions and van der Put series, respectively.

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Denote via  $\mathcal{I}^\infty$  and  $\mathcal{O}^\infty$  the sets of infinite words over input alphabet  $\mathcal{I}$  and output alphabet  $\mathcal{O}$ , respectively.

**Theorem (R.I. Grigorchuk, V.V.Nekrashevich, V.I. Sushchanskii)**

The mapping  $f: \mathcal{I}^\infty \rightarrow \mathcal{O}^\infty$  is continuous if and only if it is defined by a certain asynchronous automaton.

Note, in general case, an asynchronous automaton defined a continuous mapping is infinite.

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The mapping  $f: \mathcal{I}^\infty \rightarrow \mathcal{O}^\infty$  is continuous if and only if it is defined by a certain asynchronous automaton.

Note, in general case, an asynchronous automaton defined a continuous mapping is infinite.

If the mapping  $f: \mathcal{I}^\infty \rightarrow \mathcal{O}^\infty$  is bijective, then this mapping is a homeomorphism, and the inverse mapping  $f^{-1}$  is also defined by a certain asynchronous automaton.

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So, if the input and output alphabets of automaton coincide (i.e.  $\mathcal{I} = \mathcal{O} = \mathbb{F}_p$ ) and the automaton is initial (i.e., has an initial state  $s_0$ ), then it induces a transformation of the space of words into itself. These words may be either finite or infinite. In the latter case, we have a continuous (in particular, 1-Lipschitz) transformation of the space of infinite words (i.e., the space of  $p$ -adic integers  $\mathbb{Z}_p$ ). Conversely, any continuous transformation is defined by a certain automaton.

# Mappings with delay

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A mapping  $f_{\mathcal{B}}: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is called  *$n$ -unit delay* whenever given an asynchronous automaton  $\mathcal{B} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, S, O, s_0)$  translated infinite input string  $\alpha = \dots \alpha_2 \alpha_1 \alpha_0$  over  $\mathbb{F}_p$  into infinite output string  $\beta = \dots \beta_2 \beta_1 \beta_0$  over  $\mathbb{F}_p$  such that  $g(\delta_i(\alpha), s_i) = \emptyset$ , where  $\emptyset$  is empty word, for  $i = 0, 1, 2, \dots, n-1$ ,  $s_i = h(\delta_{i-1}(\alpha), s_{i-1})$ ,  $i = 1, 2, \dots, n-1$ ; and  $g(\delta_{n+i}(\alpha), s_{n+i}) = \beta_i$ ,  $i = 0, 1, \dots$ ,  
 $s_{n+i} = h(\delta_{n+i-1}(\alpha), s_{n+i-1})$  for  $i = 0, 1, 2, \dots$

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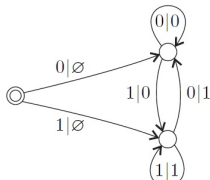
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A mapping  $f_{\mathcal{B}}: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is called  *$n$ -unit delay* whenever given an asynchronous automaton  $\mathcal{B} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, \mathcal{S}, O, s_0)$  translated infinite input string  $\alpha = \dots \alpha_2 \alpha_1 \alpha_0$  over  $\mathbb{F}_p$  into infinite output string  $\beta = \dots \beta_2 \beta_1 \beta_0$  over  $\mathbb{F}_p$  such that  $g(\delta_i(\alpha), s_i) = \emptyset$ , where  $\emptyset$  is empty word, for  $i = 0, 1, 2, \dots, n-1$ ,  $s_i = h(\delta_{i-1}(\alpha), s_{i-1})$ ,  $i = 1, 2, \dots, n-1$ ; and  $g(\delta_{n+i}(\alpha), s_{n+i}) = \beta_i$ ,  $i = 0, 1, \dots$ ,  $s_{n+i} = h(\delta_{n+i-1}(\alpha), s_{n+i-1})$  for  $i = 0, 1, 2, \dots$

Example of unit-delay map ( $n = 1$ ):



# Mappings with delay

In general case, an  $n$ -unit delay mappings form a class of a continuous functions, that in turn, contains a class of shifts.

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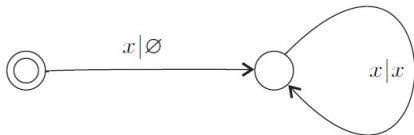
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# Mappings with delay

In general case, an  $n$ -unit delay mappings form a class of a continuous functions, that in turn, contains a class of shifts. For example, a class of **unit-delay** mappings contains **unilateral shift** defined by finite asynchronous automaton, that is irrespective of the first incoming letter  $x \in \mathbb{F}_p$ , outputs an empty word  $\emptyset$ ; after that, an automaton outputs the incoming word without changes:



# Shifts

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The  $p$ -adic shift  $\mathbf{S}: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is defined as follows.

If  $x = x_0 + x_1p + x_2p^2 + \dots$ , where the  $x_i \in \mathbb{F}_p = \{0, 1, \dots, p-1\}$ , we let  $\mathbf{S}(x) = x_1 + x_2p + x_3p^2 + \dots$

We see that if  $\mathbf{S}^k$  denotes the  $k$ -fold iterate of  $\mathbf{S}$ , then we have that  $\mathbf{S}^k(x) = x_k + x_{k+1}p + \dots$ . Moreover, for  $x \in \mathbb{Z}$  it is the case that  $\mathbf{S}^k(x) = \lfloor \frac{x}{p^k} \rfloor$  where  $\lfloor \cdot \rfloor$  is the greatest integer function.

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The  $p$ -adic shift is continuous as a function of  $\mathbb{Z}_p$ : if  $\|x - y\|_p < p^{-(k+1)}$  then  $\|\mathbf{S}(x) - \mathbf{S}(y)\|_p < p^{-k}$ .

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By Mahler's Theorem, any continuous function  $T: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  can be expressed in the form of a uniformly convergent series, called its *Mahler Expansion*:

$$T(x) = \sum_{m=0}^{\infty} a_m \binom{x}{m}$$

where

$$a_m = \sum_{i=0}^m (-1)^i \binom{m}{i} T(m-i) \in \mathbb{Z}_p$$

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We let  $a_m^{(k)}$  be the  $m^{\text{th}}$  Mahler coefficient of  $\mathbf{S}^k$ :

$$\mathbf{S}^k(x) = \sum_{m=0}^{\infty} a_m^{(k)} \binom{x}{m}.$$

**Theorem.** (J.Kingsbery, A. Levin, A. Preygel, C.E. Silva)

The coefficients  $a_m^{(k)}$  satisfy the following properties:

- 1**  $a_m^{(k)} = 0$  for  $0 \leq m < p^k$ ;
- 2**  $a_m^{(k)} = 1$  for  $m = p^k$ ;
- 3** Suppose  $j \geq 0$ . Then  $p^j$  divides  $a_m^{(k)}$  for  $m > jp^k - j + 1$  (and so,  $\|a_m^{(k)}\|_p \leq p^{-j}$ ).

# 1-Lipschitz functions

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This theorem describes synchronous automata (in other words, 1-Lipschitz functions) in terms of Mahler expansion.

**Theorem. (A.S. Anashin)**

A function  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  represented by Mahler expansion is 1-Lipschitz if and only if

$$\|a_i\|_p \leq p^{-[\log_p i]}$$

for all  $i = 1, 2, \dots$

Recall that for  $i \in \mathbb{N}$  a number  $[\log_p i]$  is reduced by 1 a number of digits in a base- $p$  expansion for  $i$ .

# n-unit delay functions

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For  $n$ -unit delay mapping,  $n \in \mathbb{N}$ , we get next theorem.

## Theorem 1

*A function  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  represented by Mahler expansion*

$$f(x) = \sum_{m=0}^{\infty} a_m \binom{x}{m},$$

*where  $a_m \in \mathbb{Z}_p$ ,  $m = 0, 1, 2, \dots$ , is an  $n$ -unit delay if and only if*

$$\|a_i\|_p \leq p^{-[\log_p n i] + 1}$$

*for all  $i \geq 1$ .*

# Dynamics

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**Dynamical system on a measurable space  $\mathbb{S}$**  is understood as a triple  $(\mathbb{S}, \mu, f)$ , where  $\mathbb{S}$  is a set endowed with a measure  $\mu$ , and  $f : \mathbb{S} \rightarrow \mathbb{S}$  is a **measurable function**.



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**Dynamical system on a measurable space  $\mathbb{S}$**  is understood as a triple  $(\mathbb{S}, \mu, f)$ , where  $\mathbb{S}$  is a set endowed with a measure  $\mu$ , and  $f : \mathbb{S} \rightarrow \mathbb{S}$  is a **measurable function**. A dynamical system is also may be topological since configuration space  $\mathbb{S}$  is not only measure space but also may be metric space, and corresponding transformation  $f$  is not only measurable but also will be **continuous**. A **orbit** of the dynamical system is a sequense  $x_0, x_1 = f(x_0), \dots, x_i = f(x_{i-1}) = f^i(x_0), \dots$  of points of the space  $\mathbb{S}$ ,  $x_0$  is called an **initial** point of the orbit. Dynamics studies a behavior of such orbits.

# Measure-preservation and ergodicity

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A mapping  $F: \mathbb{S} \rightarrow \mathbb{S}$  of measurable space  $\mathbb{S}$  onto  $\mathbb{S}$  endowed with probabilistic measure  $\mu$ , is said to be *measure-preserving* whenever  $\mu(F^{-1}(S)) = \mu(S)$  for each measurable subset  $S \subseteq \mathbb{S}$ .

A measure-preserving map  $F: \mathbb{S} \rightarrow \mathbb{S}$  is said to be *ergodic* if for each measurable subset  $S$  such that  $F^{-1}(S) = S$  holds either  $\mu(S) = 1$  or  $\mu(S) = 0$ .

# Automata as $p$ -adic dynamical systems

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We study dynamical system  $(\mathbb{Z}_p, \mu, f)$  on  $\mathbb{Z}_p$ , where map  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  defined by some **asynchronous automaton**  $\mathcal{B} = (\mathbb{F}_p, \mathcal{S}, \mathbb{F}_p, \mathcal{S}, O, s_0)$ . The ring  $\mathbb{Z}_p$  can be endowed with a probability measure  $\mu_p$ . The measure  $\mu_p$  is a normalized **Haar measure**. The base of elementary measurable subsets are all balls  $B_{p^{-k}}(a)$  of non-zero radii  $p^{-k}$ ; and we put

$$\mu_p(B_{p^{-k}}(a)) = p^{-k}.$$

# Measure-preservation and ergodicity of 1-Lipschitz functions in terms of Mahler expansion

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## Theorem. (V.S. Anashin)

The function  $f$  defines a 1-Lipschitz measure-preserving transformation on  $\mathbb{Z}_p$  whenever the following conditions hold simultaneously:

- 1  $a_1 \not\equiv 0 \pmod{p}$ ;
- 2  $a_i \equiv 0 \pmod{p^{\lfloor \log_p i \rfloor + 1}}$ ,  $i = 2, 3, \dots$

The function  $f$  defines a 1-Lipschitz ergodic transformation on  $\mathbb{Z}_p$  whenever the following conditions hold simultaneously:

- 1  $a_0 \not\equiv 0 \pmod{p}$ ;
- 2  $a_1 \equiv 1 \pmod{p}$ , for  $p$  odd;
- 3  $a_1 \equiv 1 \pmod{4}$ , for  $p = 2$ ;
- 4  $a_i \equiv 0 \pmod{p^{\lfloor \log_p(i+1) \rfloor + 1}}$ ,  $i = 2, 3, \dots$

Moreover, in the case  $p = 2$  these conditions are necessary.



# Preserve the measure for n-unit delay mappings

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Let  $F_k$  be a reduction of function  $f \bmod p^{n \cdot (k-1)}$  on the elements of the ring  $\mathbb{Z}/p^{n \cdot k}\mathbb{Z}$  for  $k = 2, 3, \dots$

## Theorem 2

*A  $n$ -unit delay mapping  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is measure-preserving if and only if the number  $\#F_k^{-1}(x)$  of  $F_k$ -pre-images of the point  $x \in \mathbb{Z}/p^{n \cdot (k-1)}\mathbb{Z}$  is equal  $p^n$ ,  $k = 2, 3, \dots$*

# Ergodicity

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A point  $x_0 \in \mathbb{Z}_p$  is said to be a *periodic point* if there exists  $r \in \mathbb{N}$  such that  $f^r(x_0) = x_0$ . The least  $r$  with this property is called the *length* of period of  $x_0$ . If  $x_0$  has period  $r$ , it is called an  *$r$ -periodic point*. The orbit of an  $r$ -periodic point  $x_0$  is  $\{x_0, x_1, \dots, x_{r-1}\}$ , where  $x_j = f^j(x_0)$ ,  $0 \leq j \leq r - 1$ . This orbit is called an  *$r$ -cycle*.

# Ergodicity

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Let  $\gamma(k)$  be an  $r(k)$ -cycle  $\{x_0, x_1, \dots, x_{r(k)-1}\}$ , where

$$x_j = (f \bmod p^{k \cdot n})^j(x_0), \quad 0 \leq j \leq r(k) - 1,$$

$k = 1, 2, 3, \dots$

## Theorem 3

*A measure-preserving a  $n$ -unit delay mapping  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is ergodic if a  $\gamma(k)$  is an unique cycle, for all  $k \in \mathbb{N}$ .*



# Measure-preservation and ergodicity in terms of Mahler expansion

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Let  $n$ -unit delay function  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  be represented by Mahler expansion

$$f(x) = \sum_{m=0}^{\infty} a_m \binom{x}{m},$$

where  $a_m \in \mathbb{Z}_p$ ,  $m = 0, 1, 2, \dots$

## Theorem 4

*A  $n$ -unit delay mapping  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is measure-preserving whenever the following conditions hold simultaneously:*

- $a_i \not\equiv 0 \pmod{p}$  for  $i = p^n$ ;
- $a_i \equiv 0 \pmod{p^{\lfloor \log_p i \rfloor}}$ ,  $i > p^n$ .

# Measure-preservation and ergodicity in terms of Mahler expansion

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$$f(x) = \sum_{m=0}^{\infty} a_m \binom{x}{m},$$

where  $a_m \in \mathbb{Z}_p$ ,  $m = 0, 1, 2, \dots$

## Theorem 5

*Let  $p = 3$ . Then a  $n$ -unit delay mapping  $f: \mathbb{Z}_p \rightarrow \mathbb{Z}_p$  is ergodic on  $\mathbb{Z}_p$  whenever the following conditions hold simultaneously:*

- 1**  $a_1 + a_2 + \dots + a_{p^n-1} \equiv 0 \pmod{p}$ ;
- 2**  $a_i \equiv 1 \pmod{p}$  for  $i = p^n$ ;
- 3**  $a_i \equiv 0 \pmod{p^{\lfloor \log_p i \rfloor}}$ ,  $i > p^n$ .

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Thank you!

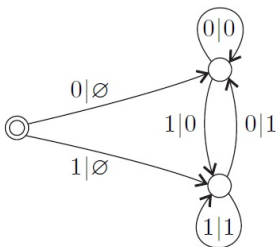
# Asynchronous automaton

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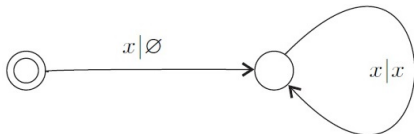
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# Unilateral shift

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